

Do Suggested HW for Section 1.1

Problems are on D2L.

List of problems and
full solutions are on website.

Definition: Consider the expression: \vec{v} in \mathbb{R}^n . This means that \vec{v} has n components, and each component is a real number.

Example: Draw $\vec{v} = [1, 3, 2]$ in \mathbb{R}^3 .

Definition: The **zero vector** is written $\vec{0}$. Each of its components is zero. The zero vector is useful for algebra.

Example: Write the zero vector in \mathbb{R}^2 and \mathbb{R}^3 .

$$\vec{0} = [0, 0] \text{ in } \mathbb{R}^2 \quad \text{and} \quad \vec{0} = [0, 0, 0] \text{ in } \mathbb{R}^3$$

Example: Let \vec{u} be in \mathbb{R}^2 . Show (prove) that $\vec{u} + (-\vec{u}) = \vec{0}$.

$$\text{Let } \vec{u} = [u_1, u_2]$$

Start with the more complicated side.

$$\begin{aligned} \vec{u} + (-\vec{u}) &= [u_1, u_2] + [-u_1, -u_2] \\ &= [u_1 - u_1, u_2 - u_2] \\ &= [0, 0] \\ &= \vec{0} \end{aligned}$$

Example: Solve for \vec{x} given that $7\vec{x} - \vec{a} = 3(\vec{a} + 4\vec{x})$.

$$\begin{aligned} 7\vec{x} - \vec{a} &= 3\vec{a} + 12\vec{x} \\ -5\vec{x} &= 4\vec{a} \\ \vec{x} &= -\frac{4}{5}\vec{a} \end{aligned}$$

Definition: Consider the statement:

\vec{w} is a **linear combination** of $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 2 \end{bmatrix}$ with coefficients -3 and 2 .

This means that $\vec{w} = -3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 2 \end{bmatrix}$.

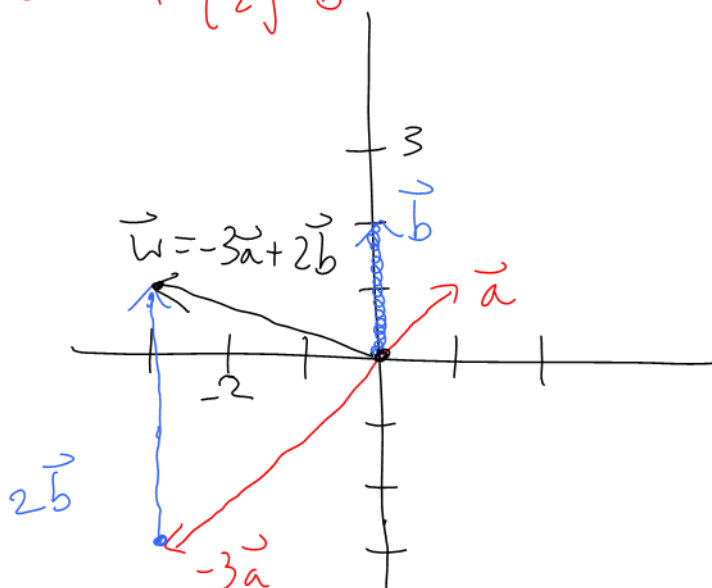
Example: Let $\vec{w} = -3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 2 \end{bmatrix}$.

a) Find \vec{w} algebraically.

$$\begin{aligned} \vec{w} &= \begin{bmatrix} -3 \\ -3 \end{bmatrix} + \begin{bmatrix} 0 \\ 4 \end{bmatrix} \\ &= \begin{bmatrix} -3 \\ 1 \end{bmatrix} \end{aligned}$$

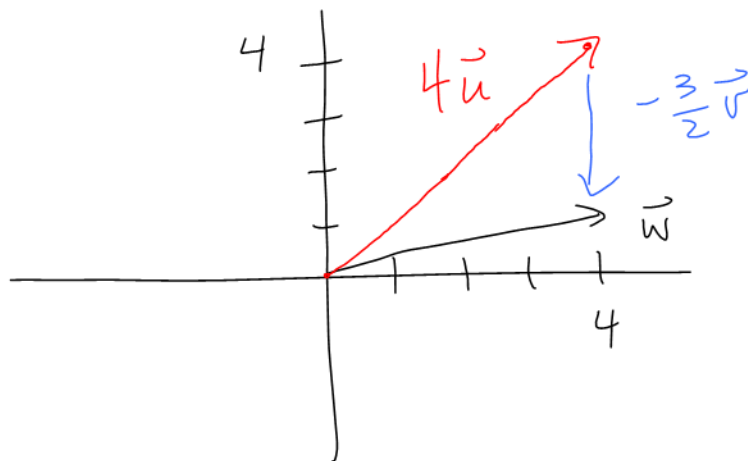
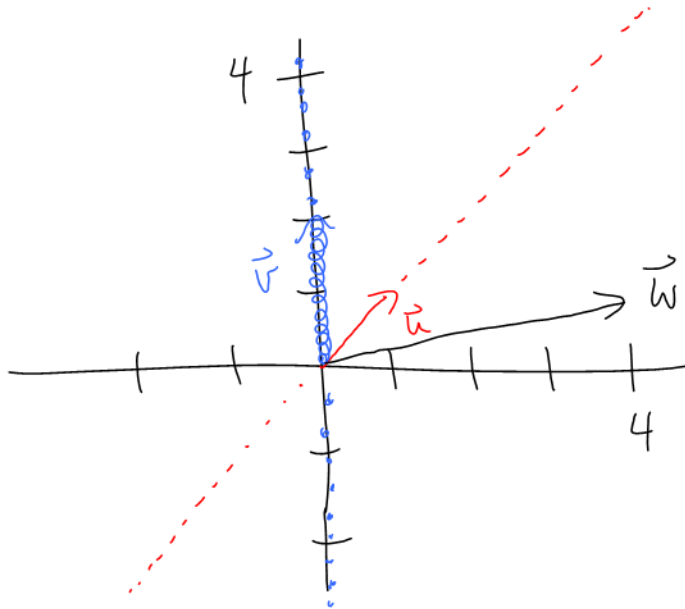
b) Find \vec{w} geometrically.

Let $\begin{bmatrix} 1 \\ 1 \end{bmatrix} = \vec{a}$ and $\begin{bmatrix} 0 \\ 2 \end{bmatrix} = \vec{b}$



Example: Write $\vec{w} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ as a linear combination of $\vec{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$ by graphing.

Think of \vec{u} and \vec{v} as the axes.

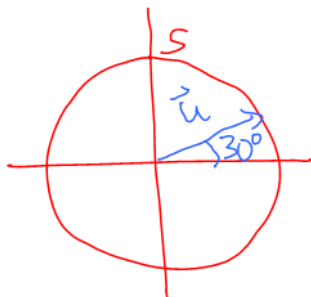


$$\begin{aligned} k \begin{bmatrix} 0 \\ 2 \end{bmatrix} &= \begin{bmatrix} 0 \\ -3 \end{bmatrix} \\ k(2) &= -3 \\ k &= -\frac{3}{2} \end{aligned}$$

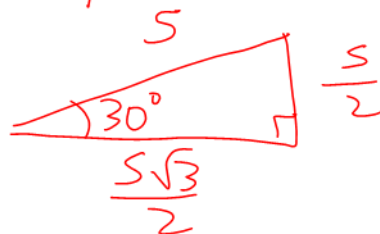
$$\vec{w} = 4\vec{u} - \frac{3}{2}\vec{v}$$

We'll do this algebraically in Ch 2.
 Let $\begin{bmatrix} 4 \\ 1 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 2 \end{bmatrix}$
 system of equations

Example: a) Let \vec{u} be a vector of length 5, in standard position, rotated 30° from the positive x -axis. Find \vec{u} algebraically.

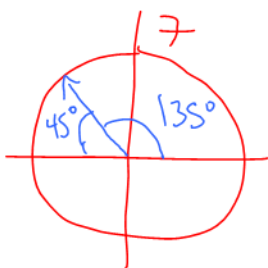


Multiply all sides by $\frac{5}{2}$:

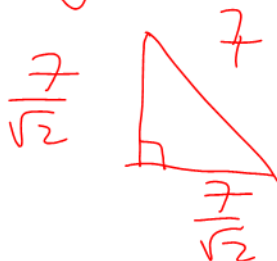


$$\vec{u} = \left[\frac{5\sqrt{3}}{2}, \frac{5}{2} \right]$$

b) Let \vec{v} be a vector of length 7, in standard position, rotated 135° from the positive x -axis. Find \vec{v} algebraically.



Multiply all sides by $\frac{7}{\sqrt{2}}$:



$$\vec{v} = \left[-\frac{7}{\sqrt{2}}, \frac{7}{\sqrt{2}} \right]$$

Watch signs!

Comment: Vectors are often used to represent velocity, acceleration or forces. The vector's direction represents the direction of the velocity/acceleration/force. The vector's length represents the magnitude of the velocity/acceleration/force.

Notation : A vector can be written as
 \vec{u} or \overrightarrow{u} or **u** \leftarrow bold font

Notation: \vec{a} is a vector
 a is a vector
 a is a real number

1.2 Length and Angle

Example: Let $\vec{u} = [1, 4, 2, -9]$ and $\vec{v} = [2, 3, -2, -1]$. Calculate the dot product $\vec{u} \cdot \vec{v}$

$$\begin{aligned}\vec{u} \cdot \vec{v} &= 1(2) + 4(3) + 2(-2) + (-9)(-1) \\ &= 19\end{aligned}$$

Example: Calculate:

a) $[1, 5] \cdot [2, -3]$

$$\begin{aligned}&= 1(2) + 5(-3) \\ &= -13\end{aligned}$$

b) $[1, 5] \cdot [2, -3, 0]$

undefined

c) $[u_1, u_2] \cdot [u_1, u_2]$

$$= u_1^2 + u_2^2$$

Fact: Three Properties of the Dot Product

Let \vec{u}, \vec{v} be in \mathbb{R}^n . Then:

1) $\vec{u} \cdot \vec{u} \geq 0$

2) $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$

3) $\vec{u} \cdot \vec{u} = 0$ if and only if $\vec{u} = \vec{0}$

Example: Break Property 3 into two statements, and decide which is more obvious.