Example: Find a basis for
$$E_0$$
 given $A = \begin{bmatrix} 4 & 1 & -3 \\ 0 & 0 & 2 \\ 0 & 0 & -3 \end{bmatrix}$.

$$[A-\lambda I]_{0}$$

Fact: Let B be an $n \times n$ matrix. The system $B\vec{x} = \vec{0}$ has nontrivial solutions exactly when $\det B = 0$. (This follows from the Fundamental Theorem of Invertible Matrices).

Section 3.5

Fact: To find all the eigenvalues of A: Solve the equation $det(A - \lambda I) = 0$.

Example: Let's understand why solving $det(A - \lambda I) = 0$ gives the eigenvalues.

$$\begin{array}{c} \lambda \text{ is an eigenvalue of A} \\ \iff A \overrightarrow{\lambda} = \lambda \overrightarrow{\lambda} \text{ for } \overrightarrow{\lambda} + \overrightarrow{\delta} \\ \iff (A - \lambda \overrightarrow{L}) \overrightarrow{\lambda} = \overrightarrow{\delta} \text{ for } \overrightarrow{\lambda} \neq \overrightarrow{\delta} \\ \iff det(A - \lambda \overrightarrow{L}) = 0 \end{array}$$

Example: Find all the eigenvalues of $A = \begin{bmatrix} 4 & -2 \\ 5 & -7 \end{bmatrix}$.

Example: Find a basis for
$$E_{-6}$$
 given $A = \begin{bmatrix} 4 & -2 \\ 5 & -7 \end{bmatrix}$.

$$A = -6$$

$$A + 6 = 0$$

Comment:

To find eigenvalues: Solve the equation $det(A - \lambda I) = 0$.

To find eigenvectors: Solve the system $[A - \lambda I \mid \vec{0}]$. Remember to exclude $\vec{x} = \vec{0}$.

Example: Let
$$A = \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix}$$
. Find the eigenvectors and eigenvalues geometrically.

In a problem like this, the eigenvectors will be parallel to the χ -axis and the χ -axis.

$$\frac{1}{2}$$
 = $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$A\overrightarrow{J} = \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
$$= \begin{bmatrix} -2 \\ 0 \end{bmatrix}$$
$$= -2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\lambda = -2$$
eigenvectors $\mathcal{C} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} t \quad (t \neq 0)$
or Basis for $f_{-2} = \mathcal{E} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \mathcal{F}$
or $f_{-2} = span(\begin{bmatrix} 1 \\ 0 \end{bmatrix})$

$$\vec{\chi} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \qquad \vec{A}\vec{\chi} = \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 1\vec{\chi}$$

$$\vec{\lambda} = 1 \qquad \vec{E}_1 = \text{Span}(\begin{bmatrix} 0 \\ 1 \end{bmatrix})$$

4.2 Determinants

Comment: Recall that the determinant of A is written det A or |A|. It's only defined for square matrices.

Fact: The cofactor expansion from Section 1.4 generalizes according to the following rules:

We can expand along any row or column.

The sign associated with each term follows the checkerboard pattern: $\begin{bmatrix} + & - & + & \dots \\ - & + & - & \dots \end{bmatrix}$

Example: Find det A by cofactor expansion along the second column. Calculate it again by cofactor expansion along the third row. Let $A = \begin{bmatrix} 4 & 1 & 6 \\ 1 & 2 & 3 \\ 6 & 0 & 7 \end{bmatrix}$.

$$2^{nd}$$
 Glumn:
 $|A| = -1$ $|+2$ $|-0|$

$$= -1 \left| \frac{1}{6} \frac{3}{7} \right| + 2 \left| \frac{4}{6} \frac{6}{7} \right|$$

$$= -1 \left(-11 \right) + 2 \left(-8 \right)$$

$$3^{rd}$$
 (80): $|A| = 6 \begin{vmatrix} 1 & 6 \\ 2 & 3 \end{vmatrix} - 0 \begin{vmatrix} 1 & 7 & 4 \\ 1 & 2 \end{vmatrix}$

$$= 6 (-9) + 7(7)$$

$$= -5$$

Example: Calculate |A| for
$$A = \begin{bmatrix} 1 & 6 & 2 & 3 \\ 0 & 0 & 0 & 4 \\ 2 & 1 & 1 & 6 \\ 2 & 0 & 5 & 7 \end{bmatrix}$$

$$= 4 \begin{bmatrix} 2 & 6 & 2 \\ 2 & 1 & 1 & 6 \\ 2 & 0 & 5 & 7 \end{bmatrix}$$

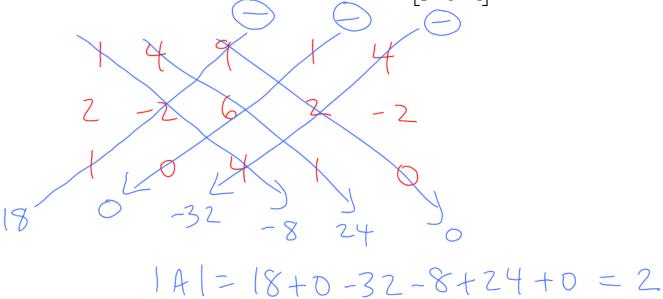
$$= 4 \begin{bmatrix} 2 & 6 & 2 \\ 2 & 1 & 1 & 6 \\ 2 & 0 & 5 & 7 \end{bmatrix}$$

$$= 4 \begin{bmatrix} 2 & 6 & 2 \\ 1 & 1 & -0 \\ 1 & 1 & -0 \end{bmatrix} + 5 \begin{bmatrix} 1 & 6 & 1 \\ 2 & 1 & 1 \\ 2 & 1 & 1 \end{bmatrix}$$

$$= 4 \begin{bmatrix} 2 & 4 & 4 \\ 4 & 4 & 1 \\ 4 & 4 & 1 \end{bmatrix}$$

Example: In this example we'll illustrate the **Quick Method** for 3×3 Determinants.

Calculate det A using the Quick Method. Let $A = \begin{bmatrix} 1 & 4 & 9 \\ 2 & -2 & 6 \\ 1 & 0 & 4 \end{bmatrix}$.



Comment: The Quick Method only applies for 3×3 matrices.