## 2.1 Linear Systems

**Definition:** A linear equation in  $\mathbb{R}^2$  has the form ax + by = c, where a, b and c are real numbers.

**Definition:** A linear system in  $\mathbb{R}^2$  consists of two or more linear equations. It's often just called a system.

**Comment:** Here's an example of a system:

2x + 6y = -14-3x + 3y = -15

Fact: A system can have: no solution, one unique solution or infinitely-many solutions.



Definition: A system with no solution is called an <u>inconsistent system</u>. (unsolute) A consistent system has one solution or infinitely-many solutions. In other words, a consistent system is solvable.

**Definition:** Consider the system:

$$2x + 6y = -14$$
$$-3x + 3y = -15$$

The matrix  $\begin{bmatrix} 2 & 6 \\ -3 & 3 \end{bmatrix}$  is called the **coefficient matrix**. The matrix  $\begin{bmatrix} 2 & 6 \\ -3 & 3 \\ -15 \end{bmatrix}$  is called the **augmented matrix**. **Fact:** There are three types of elementary row operations that can be performed on an augmented matrix. These row operations don't change the solution of the system:

- 1) Swap two rows
- 2) Multiply or divide a row by a nonzero real number
- 3) (Current Row)  $\pm$ #(Pivot Row)

**Example:** Solve by elimination:

Example: Solve:

$$2x - 3y = 8$$

$$-4x + 6y = 20$$

$$\begin{bmatrix} 2 & -3 & 8 \\ -4 & 6 & 20 \end{bmatrix}$$

$$\frac{1}{-4} \begin{bmatrix} 1 & -\frac{3}{2} & 4 \\ -4 & 6 & 20 \end{bmatrix}$$

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Fact: A system has no solution if the following type of row appears while performing row operations:
[ all zeros | nonzero]

Example: Solve:

(y=

$$2x - 3y = 8$$

$$-4x + 6y = -16$$

$$\begin{bmatrix} 2 & -3 & | & 8 \\ -4 & 6 & | & -16 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -\frac{3}{2} & | & 4 \\ -4 & 6 & | & -16 \end{bmatrix}$$

$$R_2 + 4R_1 = 0 \quad (1 - \frac{3}{2}) = 4$$

$$R_2 + 4R_1 = 0 \quad (2 - \frac{3}{2}) = 0$$

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$$R_2 + 4R_1 = 0 \quad (2 - \frac{3}{2}) = 0$$

$$R_2$$

Example: Solve:

$$x = 5$$

$$2x + 3y = 4$$

$$3x + 4y = 7$$

$$\begin{pmatrix} 2 & 3 & | & 4 \\ 3x + 4y = 7 \end{pmatrix}$$

$$Get \quad 0'_{5} \quad in rest \quad of \quad 6 \quad lumn \\ R_{2} - 2R_{1} \begin{bmatrix} 1 & 0 & | & 5 \\ 0 & 3 & | & -6 \\ 0 & 4 & | & -8 \end{bmatrix}$$

$$\frac{R_{2}}{3} \begin{bmatrix} 1 & 0 & | & 5 \\ 0 & 4 & | & -8 \end{bmatrix}$$

$$\frac{R_{2}}{3} \begin{bmatrix} 1 & 0 & | & 5 \\ 0 & 4 & | & -8 \end{bmatrix}$$

$$R_{3} - 4R_{2} \begin{bmatrix} 0 & 0 & | & 5 \\ 0 & 4 & | & -8 \end{bmatrix}$$

$$\chi = -2$$

$$\begin{cases} y = -2 \\ y = -2 \\ y = -2 \end{bmatrix}$$

$$l \quad vique \quad s = lution$$

**Definition:** Back-substitution is the process of solving a sytem from the bottom equation upwards.

**Example:** Solve by back-substitution:

$$4x + y + z = 15$$

$$3y + 5z = 29$$

$$2z = 8$$

$$2z = 8 \implies z = 4$$

$$3y + Sz = 29 \implies 3y + 70 = 29 \implies y = 3$$

$$4x + y + z = 15 \implies 4x + 3 + 4 = 15 \implies x = 2$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$$

**Comment:** Most systems can't be solved by back-substitution.

## 2.2 Solving Systems

**Definition:** A matrix is in **row-echelon form** (REF) if: any zero rows are at the bottom AND the leading nonzero entries of each row move down and right

**Comment:** The following matrices are in REF:

| (6) 0 | -1] | (2) 3 -1] |
|-------|-----|-----------|
| 0 0 ( | 3   | 047       |
| 0 0   | 0   |           |

**Definition:** An augmented matrix is in REF if the coefficient matrix is in REF.

**Comment:** The following matrices are in REF:

| [6]0 - | -1   1 ] |        | 0 ] |
|--------|----------|--------|-----|
| 0 0 (  | 3 2      | 0(4) 7 | 0   |
| 0 0    | 0 3      |        | 9   |

**Definition:** One method of solving a system is **Gaussian Elimination**. The augmented matrix is transformed to REF using elementary row operations. The system is then solved by back-substitution.

**Example:** Solve by Gaussian Elimination:

$$x + 2y + z = 6$$

$$2x + 2y = 8$$

$$3y + z = 8$$

$$\begin{cases} 1 & 2 & 1 & 6 \\ 2 & 2 & 0 & 9 \\ 0 & 3 & 1 & 8 \end{bmatrix}$$

$$R_{2} - 2R_{1} \begin{bmatrix} 1 & 2 & 1 & 6 \\ 0 & -2 & -2 & -4 \\ 0 & 3 & 1 & 8 \end{bmatrix}$$

$$\frac{R_{2}}{-2} \begin{bmatrix} 1 & 2 & 1 & 6 \\ 0 & -2 & -2 & -4 \\ 0 & 3 & 1 & 8 \end{bmatrix}$$

$$R_{3} - 3R_{2} \begin{bmatrix} 0 & -2 & 1 & 6 \\ 0 & -2 & -2 & -2 \\ 0 & 3 & 1 & 8 \end{bmatrix}$$

$$R_{3} - 3R_{2} \begin{bmatrix} 0 & -2 & 1 & 6 \\ 0 & -2 & -2 & -2 \\ 0 & -2 & -2 & -4 \\ 0 & -2 & -2 & -2 \\ 0 & -2 & -2 &$$

Back-substitute

$$-2z = 2 \implies z = -1$$
  

$$y + z = 2 \implies y - 1 = 2 \implies y = 3$$
  

$$z + 2y + z = 6 \implies x + 6 - 1 = 6 \implies x = 1$$
  

$$\begin{bmatrix} x \\ z \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

**Definition:** A matrix is in **reduced row-echelon form** (RREF) if: the matrix is in REF,

the leading nonzero entry in each row is 1, AND these leading ones have zeros everywhere else in their columns

Comment:The following matrices are in RREF: $\begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 

**Comment:** The following matrix is in REF but not RREF:



**Definition:** An augmented matrix is in RREF if the coefficient matrix is in RREF.

| Comment:                                      | The following matrices are in                               | RREF |
|---|---|------|
| $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} 1$ | $\begin{bmatrix} 1 \\ 5 \\ 0 \end{bmatrix} 9 \end{bmatrix}$ |      |
| 0 (1) 0 2                                     |   |      |
| $\begin{bmatrix} 0 & 0 \\ 1 \end{bmatrix} 3$  |   |      |

**Definition:** Another method of solving a system is **Gauss-Jordan Elimination**. The augmented matrix is transformed to RREF using elementary row operations. This is typically faster than Gaussian Elimination.