

Definition: An **elementary matrix** represents a row operation.

To identify which operation, consider how I has been transformed. For example:

$$E = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \text{ represents } 2R_1$$

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$E = \begin{bmatrix} 1 & 0 \\ 0 & -4 \end{bmatrix} \text{ represents } -4R_2$$

$$E = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \text{ represents } R_2 + 3R_1$$

$$E = \begin{bmatrix} 1 & -5 \\ 0 & 1 \end{bmatrix} \text{ represents } R_1 - 5R_2$$

$$E = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ represents } R_1 \leftrightarrow R_2$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \text{ represents } R_2 \leftrightarrow R_3$$

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 6 \\ 0 & 0 & 1 \end{bmatrix} \text{ represents } R_2 + 6R_3$$

Example: State the row operation that is represented by the elementary matrix. Then find the inverse matrix.

a) $E_1 = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$

represents $3R_1$

$\frac{1}{3}R_1$ undoes it

$$E_1^{-1} = \begin{bmatrix} \frac{1}{3} & 0 \\ 0 & 1 \end{bmatrix}$$

b) $E_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

represents $R_1 \leftrightarrow R_2$

$R_1 \leftrightarrow R_2$ undoes it

$$E_2^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

c) $E_3 = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$

represents $R_2 + 2R_1$

$R_2 - 2R_1$ undoes it

$$E_3^{-1} = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

Fact: An elementary matrix acts on the **left** of a matrix. When an elementary matrix is multiplied on the left of A , it performs the associated row operation on A . For example:

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 2a & 2b \\ c & d \end{bmatrix}.$$

Example: Let $A = \begin{bmatrix} 2 & 1 \\ 0 & 1 \end{bmatrix}$. Write A and A^{-1} as a product of elementary matrices.

$$\frac{R_1}{2} \quad \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix} \quad E_1 = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \quad E_1^{-1} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \quad (2R_1)$$

$$R_1 - \frac{1}{2}R_2 \quad \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad E_2 = \begin{bmatrix} 1 & -\frac{1}{2} \\ 0 & 1 \end{bmatrix} \quad E_2^{-1} = \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix} \quad (R_1 + \frac{1}{2}R_2)$$

$$\underbrace{E_2 E_1 A}_{A^{-1}} = I$$

$$A^{-1} = E_2 E_1 \quad \checkmark$$

$$\begin{aligned} A &= (A^{-1})^{-1} \\ &= (E_2 E_1)^{-1} \\ &= E_1^{-1} E_2^{-1} \quad \checkmark \end{aligned}$$

3.3 The Inverse of a Matrix

Example: Let $A = \begin{bmatrix} 2 & 4 \\ 1 & 1 \end{bmatrix}$. Write A and A^{-1} as a product of elementary matrices.

$$\frac{R_1}{2} \quad \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \quad E_1 = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & 1 \end{bmatrix} \quad E_1^{-1} = \begin{matrix} (2R_1) \\ \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \end{matrix}$$

$$R_2 - R_1 \quad \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} \quad E_2 = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \quad E_2^{-1} = \begin{matrix} (R_2 + R_1) \\ \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \end{matrix}$$

$$\frac{R_2}{(-1)} \quad \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \quad E_3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad E_3^{-1} = \begin{matrix} (-R_2) \\ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \end{matrix}$$

$$R_1 - 2R_2 \quad \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad E_4 = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \quad E_4^{-1} = \begin{matrix} (R_1 + 2R_2) \\ \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \end{matrix}$$

$$\underbrace{E_4 E_3 E_2 E_1}_A A = I$$

$$A^{-1} = E_4 E_3 E_2 E_1 \quad \checkmark$$

$$\begin{aligned} A &= (A^{-1})^{-1} \\ &= (E_4 E_3 E_2 E_1)^{-1} \\ &= E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} \quad \checkmark \end{aligned}$$

The Fundamental Theorem of Invertible Matrices

Let A be an $n \times n$ matrix. The following statements are equivalent:

- a) A is invertible.
- b) $A\mathbf{x} = \mathbf{b}$ has a unique solution for every \mathbf{b} in \mathbb{R}^n .
- c) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
- d) The RREF of A is I .
- e) A is a product of elementary matrices.

Comment: Consider the Fundamental Theorem of Invertible Matrices. For a given $n \times n$ matrix, the five statements are **all true** or **all false**.

Example: Consider the Fundamental Theorem of Invertible Matrices. Which of the five statements are true for A ?

a) $A = \begin{bmatrix} 1 & 4 \\ 6 & 9 \end{bmatrix}$

$$\det A \neq 0 \\ \Rightarrow A \text{ is invertible}$$

All five statements are true for A .

b) $A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$

$$\det A = 0 \\ \Rightarrow A \text{ is not invertible}$$

None of the five statements are true for A .

3.4 LU Factorization

Definition: An upper triangular matrix is a square matrix with zeros below the main diagonal. An example is

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix}$$

Definition: A lower triangular matrix is a square matrix with zeros above the main diagonal. An example is

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ 4 & 5 & 6 \end{bmatrix}$$

Definition: A unit lower triangular matrix is lower triangular and has ones on the main diagonal. An example is

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 4 & 5 & 1 \end{bmatrix}$$

Definition: The LU Factorization of a square matrix A is $A = LU$, where L is a unit lower triangular matrix and U is an upper triangular matrix.

Comment: Here is an LU Factorization:

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & 4 & 3 \\ 8 & 10 & 13 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 4 & 3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 6 \end{bmatrix}$$

$$A = L U$$

Example: Solve the system below using the LU Factorization on the previous page.

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & 4 & 3 \\ 8 & 10 & 13 \end{bmatrix} \vec{x} = \begin{bmatrix} 1 \\ 2 \\ -8 \end{bmatrix}$$

$$A\vec{x} = \vec{b}$$

$$LU\vec{x} = \vec{b}$$

$\underbrace{LU}_{\vec{y}}$

① Solve $L\vec{y} = \vec{b}$ to get \vec{y}

② Solve $U\vec{x} = \vec{y}$ to get \vec{x}

$$\textcircled{1} L\vec{y} = \vec{b} : \begin{bmatrix} 1 & 0 & 0 & | & 1 \\ 2 & 1 & 0 & | & 2 \\ 4 & 3 & 1 & | & -8 \end{bmatrix}$$

$$y_1 = 1$$

$$2y_1 + y_2 = 2 \Rightarrow 2 + y_2 = 2 \Rightarrow y_2 = 0$$

$$4y_1 + 3y_2 + y_3 = -8 \Rightarrow 4 + 0 + y_3 = -8 \Rightarrow y_3 = -12$$

$$\textcircled{2} U\vec{x} = \vec{y} : \begin{bmatrix} 2 & 1 & 1 & | & 1 \\ 0 & 2 & 1 & | & 0 \\ 0 & 0 & 6 & | & -12 \end{bmatrix}$$

$$\begin{aligned} 6x_3 &= -12 \\ \Rightarrow x_3 &= -2 \end{aligned}$$

$$\begin{aligned} 2x_2 + x_3 &= 0 \\ \Rightarrow x_2 &= 1 \end{aligned}$$

$$\begin{aligned} 2x_1 + x_2 + x_3 &= 1 \\ \Rightarrow x_1 &= 1 \end{aligned} \quad \vec{x} = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$$