Example: Are
$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$
, $\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$ linearly independent?

Let
$$C_{1}\begin{bmatrix} 1 \\ 0 \end{bmatrix} + C_{2}\begin{bmatrix} 1 \\ 0 \end{bmatrix} + C_{3}\begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

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$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} C_{1} & C_{2} & C_{3} & 0 \\ 0 & -1 & 2 & 0 \end{bmatrix}$$

Yes. Vectors are linearly independent.

Fact: A set of more than n vectors in \mathbb{R}^n is linearly dependent. For example three vectors in \mathbb{R}^2 are guaranteed to be linearly dependent.

Example: Let's explore why this fact is true.

Let
$$GV_1 + (zV_2 + ... + C_m) = 0$$

$$C_1 C_2 ... C_m = 0$$

$$M > N$$

System is solvable because
$$C_1 = C_2 = \cdots = C_m = 0$$
 solves the system.

[1]

[2]

[3]

RREF

Solution has at teast 1 parameter.

Example: Find a linear dependence relationship (linear dependency) involving $\begin{bmatrix} 1 \\ 6 \end{bmatrix}$, $\begin{bmatrix} 2 \\ 6 \end{bmatrix}$ and $\begin{bmatrix} 4 \\ 30 \end{bmatrix}$. Start by letting $c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 = \vec{0}$.

Let t be any nonzero real #: t=1 $C_1 = -6$, $C_2 = 1$, $C_3 = 1$ $C_1 \vec{v}_1 + C_2 \vec{v}_2 + C_3 \vec{v}_3 = 0$ $-6 \vec{v}_1 + \vec{v}_2 + \vec{v}_3 = 0$

Example: Find a linear dependence relationship (linear dependency) involving $\begin{bmatrix} 1 \\ 6 \end{bmatrix}$, $\begin{bmatrix} 2 \\ 6 \end{bmatrix}$ and $\begin{bmatrix} 4 \\ 30 \end{bmatrix}$. Start by putting the vectors into the rows of a matrix.

$$\frac{\vec{v}_{1}}{\vec{v}_{2}} \left[\frac{1}{2} + \frac{6}{3} \right] \\
\frac{\vec{v}_{2}}{\vec{v}_{3}} \left[\frac{1}{2} + \frac{6}{3} \right] \\
\frac{\vec{v}_{2} - 2\vec{v}_{1}}{\vec{v}_{3} - 4\vec{v}_{1}} \left[\frac{1}{2} + \frac{6}{2} \right] \\
\frac{\vec{v}_{3} - 4\vec{v}_{1}}{\vec{v}_{3} - 4\vec{v}_{1}} + \frac{\vec{v}_{2} - 2\vec{v}_{1}}{\vec{v}_{3}} = 0$$

$$\frac{\vec{v}_{3} - 4\vec{v}_{1} + \vec{v}_{2} - 2\vec{v}_{1}}{-6\vec{v}_{1} + \vec{v}_{2} + \vec{v}_{3}} = 0$$

Comment: Compare the methods used in the last two examples. The first method gives the general solution, while the second method gives one particular solution.

Comment: Preview of Section 3.5:

We'll consider objects like lines or planes through the origin, and find a set of direction vectors containing the minimum number of vectors. This discussion will require knowledge of span and linear independence.

2.4 Applications of Linear Systems

Example: Find the parabola $y = ax^2 + bx + c$ that passes through (1, 12), (-1, 18) and (2, 30).

$$ax^{2} + bx + c = y$$

$$a,b,c \text{ are the variables}$$

$$(x,y) = (1,12): a + b + c = 12$$

$$(-1,18): a - b + c = 18$$

$$(2,30): 4a + 2b + c = 30$$

$$a b c$$

$$\begin{bmatrix} 1 & 1 & 1 & 12 \\ 4 & 2 & 1 & 30 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & 18 \\ 4 & 2 & 1 & 30 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 1 & 18 \\ 4 & 2 & 1 & 30 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 0 & 0 & 1 & 8 \\ 0 & 0 & 1 & 8 \end{bmatrix}$$

$$\alpha = 7, b = -3, c = 8$$

$$y = ax^{2} + bx + c$$

$$y = 7x^{2} - 3x + 8$$

Example: Balance $NH_3 + O_2 \rightarrow N_2 + H_2O$

$$W NH_3 + \times O_2 \rightarrow y N_2 + Z H_2 O$$

 W, χ, y, Z are the variables

N:
$$W = 2y = 0$$

H: $3W = 2z = 0$
O: $2x = z = 0$

To Be Entinued