

2.3 Span and Linear Independence

Example: Is $\begin{bmatrix} 8 \\ -10 \end{bmatrix}$ a linear combination of $\begin{bmatrix} -1 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ -3 \end{bmatrix}$?

Let $c_1 \begin{bmatrix} -1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ -3 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$

$$\begin{cases} -c_1 + 2c_2 = 8 \\ 2c_1 - 3c_2 = -10 \end{cases}$$

$$\begin{array}{cc|c} c_1 & c_2 & \\ \hline -1 & 2 & 8 \\ 2 & -3 & -10 \end{array}$$

$$\frac{R_1}{-1} \begin{array}{cc|c} 1 & -2 & -8 \\ 2 & -3 & -10 \end{array}$$

$$R_2 - 2R_1 \begin{array}{cc|c} 1 & -2 & -8 \\ 0 & 1 & 6 \end{array} \text{ REF}$$

System is consistent.

Yes

To check: $R_1 + 2R_2 \begin{array}{cc|c} c_1 & c_2 & \\ \hline 1 & 0 & 4 \\ 0 & 1 & 6 \end{array} \text{ RREF}$
 $c_1 = 4, c_2 = 6$

$$4 \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 6 \begin{bmatrix} 2 \\ -3 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix} \checkmark$$

Example: Is $\vec{w} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$ a linear combination of $\vec{u} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$?

$$\text{Let } c_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

linear combination of \vec{u} and \vec{v}

$$\begin{array}{cc|c} c_1 & c_2 & \\ \hline 1 & 1 & 1 \\ 0 & 3 & 1 \\ 1 & 0 & 2 \end{array}$$

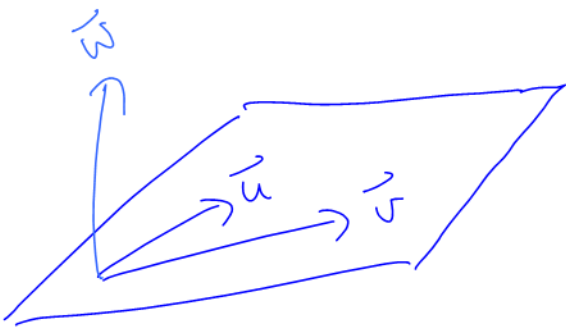
$$R_3 - R_1 \quad \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 3 & 1 \\ 0 & -1 & 1 \end{array}$$

$$\frac{R_2}{3} \quad \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & -1 & 1 \end{array}$$

$$R_3 + R_2 \quad \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & \frac{1}{3} \\ 0 & 0 & \frac{4}{3} \end{array} \text{ REF}$$

No solution

No



Fact: The vector \vec{b} is a linear combination of the columns of matrix A if and only if the system $\left[A \mid \vec{b} \right]$ is consistent.

Definition: The **span** of $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ is the set of all linear combinations of $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$.

Comment: a) $\text{span}(\vec{a}, \vec{b}) = \{ \vec{0}, 3\vec{a}, -7\vec{b}, 2\vec{a} + 5\vec{b}, \dots \}$

b) $\text{span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n) = \{ c_1\vec{u}_1 + c_2\vec{u}_2 + \dots + c_n\vec{u}_n \}$
where c_1, c_2, \dots, c_n are any real numbers.

Fact: The zero vector $\vec{0}$ is in $\text{span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n)$ because $0\vec{u}_1 + 0\vec{u}_2 + \dots + 0\vec{u}_n = \vec{0}$.

Example: Describe each span geometrically:

a) $\text{span}\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ -3 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -3 \\ -3 \end{bmatrix} \right\}$$

$$= \left\{ t \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

Line through the origin in \mathbb{R}^2 with $\vec{d} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

b) $\text{span}\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}\right)$

All of \mathbb{R}^2 (the xy-plane)

c) $\text{span}\left(\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 4 \end{bmatrix}\right)$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} -4 \\ 0 \\ 4 \end{bmatrix} \right\}$$

$$= \left\{ t \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$$

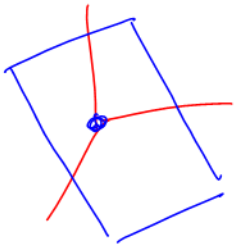
Line through the origin in \mathbb{R}^3 with $\vec{d} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$

d) $\text{span}\left(\begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}\right)$

Plane through the origin in \mathbb{R}^3 with direction vectors $\vec{u} = \begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$

Example: Find an equation for $\text{span}\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}\right)$. Give your answer in any form.

Plane through origin



NORMAL FORM

$$\vec{n} = \vec{u} \times \vec{v} \\ = [-3, -5, 3]$$

$$\vec{n} \cdot \vec{x} = \vec{n} \cdot \vec{p}$$

$$\begin{bmatrix} -3 \\ -5 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -3 \\ -5 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

✓

VECTOR FORM

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

$$\vec{x} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ 3 \\ 6 \end{bmatrix}$$

✓

1 0 1 0
~~X X X~~
 1 3 6 1 3

Example: a) Show that $\text{span}\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix}\right) = \mathbb{R}^2$. (algebra)

Let $c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$
 Show the system is solvable for c_1 and c_2 .

$$\begin{array}{cc|c} c_1 & c_2 & \\ \hline 1 & 2 & a \\ 3 & 1 & b \end{array}$$

$R_2 - 3R_1$ $\begin{bmatrix} 1 & 2 & | & a \\ 0 & -5 & | & b-3a \end{bmatrix}$ REF

System is solvable for c_1 and c_2 . ✓

b) Write $\begin{bmatrix} a \\ b \end{bmatrix}$ as a linear combination of $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

$$\begin{array}{cc|c} R_2 & & \\ \hline 1 & 2 & a \\ 0 & 1 & \frac{b-3a}{-5} \end{array}$$

$R_1 - 2R_2$ $\begin{bmatrix} 1 & 0 & | & \frac{-a}{5} + \frac{2b}{5} \\ 0 & 1 & | & \frac{3a-b}{5} \end{bmatrix}$

$$\begin{aligned} & a + \frac{2}{5}(b-3a) \\ &= a + \frac{2b}{5} - \frac{6a}{5} \\ &= -\frac{a}{5} + \frac{2b}{5} \end{aligned}$$

REF

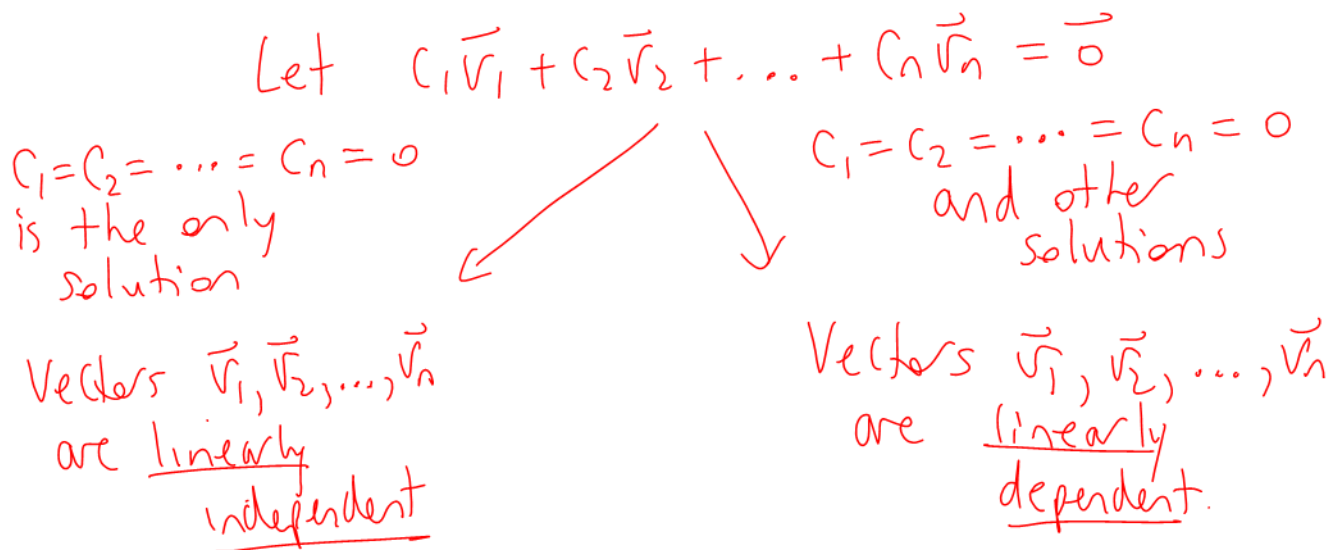
$$c_1 = -\frac{a}{5} + \frac{2b}{5}$$

$$c_2 = \frac{3a}{5} - \frac{b}{5}$$

$$\left(-\frac{a}{5} + \frac{2b}{5}\right) \begin{bmatrix} 1 \\ 3 \end{bmatrix} + \left(\frac{3a}{5} - \frac{b}{5}\right) \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \end{bmatrix}$$

Comment: To decide if a system is consistent, reduce it to REF.
To solve a system, reduce it to RREF.

Definition: Given $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$, consider solutions to $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}$. If the only solution is $c_1 = c_2 = \dots = c_n = 0$ then the set of vectors is **linearly independent**. If there are solutions other than $c_1 = c_2 = \dots = c_n = 0$ then the set of vectors is **linearly dependent**.



Comment: The two sentences below mean the same thing:
Vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly independent.
The set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent.

Comment: The two sentences below mean the same thing:
Vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly dependent.
The set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly dependent.

Comment: a) $\left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 7 \end{bmatrix} \right\}$ is linearly dependent.

$$3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 4 \end{bmatrix} - 1 \begin{bmatrix} 2 \\ 7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \checkmark$$

b) $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \end{bmatrix}$ are linearly dependent.

$$0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 1 \begin{bmatrix} 3 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Coefficients are not all zero.

c) $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ are linearly dependent.

$$1 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Coefficients are not all zero