## 2.2 Solving Systems Gnt'd

£x: Consider 
$$\begin{bmatrix} 1 & 2 & | & 0 \\ 3 & 4 & | & 0 \end{bmatrix}$$
 or  $\begin{bmatrix} 31x + 2y = 0 \\ 3x + 4y = 0 \end{bmatrix}$   
It has solution  $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ 

Terminology  $\vec{x} = \vec{0}$  is called the <u>trivial</u> solution  $\begin{bmatrix} anthing & 0 \\ 0 & \vdots \end{bmatrix}$  is called a <u>homogeneous system</u>

Fact A homogeneous system always has at least 1 solution: the trivial solution

 $\underline{Ex}$ : How many solutions to the system?

Given n>m.

At least 1 solution (because it's homogeneous)

OD. REF

At least 1 parameter => 00-many solutions

## 2.3 Span and Linear Independence

Ex: |s [8] a linear combination of  $\begin{bmatrix} -1 \\ 2 \end{bmatrix}$  and  $\begin{bmatrix} 2 \\ -3 \end{bmatrix}$ ?

Let 
$$C_1\begin{bmatrix} -1 \\ 2 \end{bmatrix} + C_2\begin{bmatrix} 2 \\ -3 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$$

$$\begin{bmatrix} -C_1 \\ 2C_1 \end{bmatrix} + \begin{bmatrix} 2C_2 \\ -3C_2 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$$

$$\begin{bmatrix} -C_1 + 2C_2 \\ 2C_1 - 3C_2 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$$

$$\begin{cases} -C_1 + 2C_2 = 8 \\ 2C_1 - 3C_2 = -10 \end{cases}$$

$$\begin{bmatrix} C_1 \\ 2 \\ -3 \end{bmatrix} = \begin{bmatrix} C_1 \\ 2 \\ -3 \end{bmatrix} = \begin{bmatrix} C_1 \\ -10 \end{bmatrix}$$

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$$R_{1}+2R_{2} \begin{bmatrix} G & C_{2} \\ 0 & 1 \end{bmatrix} + G \begin{bmatrix} 2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$$

$$C_{1}=4 \\ C_{2}=6$$

$$Yes$$

$$To check: \qquad 4 \begin{bmatrix} -1 \\ 2 \end{bmatrix} + 6 \begin{bmatrix} 2 \\ -3 \end{bmatrix} = \begin{bmatrix} 8 \\ -10 \end{bmatrix}$$

$$ext{ is } W = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \text{ a linear Gorbination}$$

$$of \qquad u = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } V = \begin{bmatrix} 1 \\ 3 \end{bmatrix} ?$$

$$C_{1} C_{2}$$

$$C_{2} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + C_{2} \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$C_{3} C_{2}$$

$$C_{1} C_{2}$$

$$C_{3} C_{2}$$

$$C_{3} C_{2}$$

$$C_{4} C_{2}$$

$$C_{5} C_{2}$$

$$C_{7} C_{2}$$

$$C_{1} C_{2}$$

$$C_{1} C_{2}$$

$$C_{3} C_{2}$$

$$C_{1} C_{2}$$

$$C_{2} C_{3} C_{2}$$

$$C_{3} C_{2}$$

$$C_{4} C_{2}$$

$$C_{5} C_{2}$$

$$C_{7} C_{2}$$

$$C_{1} C_{2}$$

$$C_{1} C_{2}$$

$$C_{1} C_{2}$$

$$C_{3} C_{2}$$

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$$C_{7} C_{2}$$

$$C_{1} C_{2}$$

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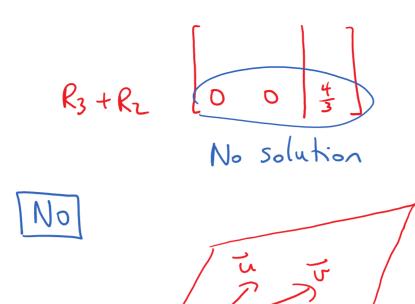
$$C_{2} C_{3}$$

$$C_{3} C_{2}$$

$$C_{4} C_{2}$$

$$C_{5} C_{2}$$

$$C_{7} C_{2}$$



Recall: A Gossistent system has at least 1 solution (is solvable)

FACT
B is a linear Combination of the Columns of A if and only if

[A 1 b ] is consistent

Def

The <u>span</u> of  $U_1, U_2, ..., U_n$  is

the set of all linear Combinations of  $U_1, U_2, ..., U_n$ .

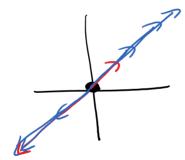
$$Ex:$$
 a) span  $(\vec{a}, \vec{b}) = \{\vec{o}, \vec{a}, 3\vec{a}, -4\vec{a}, 7\vec{b}, -7\vec{b}, \vec{a}, 5\vec{b}, -1|\vec{a}, 8\vec{b}, ...\}$ 

b) span 
$$(\vec{u}_1, ..., \vec{u}_n) = \{C_1\vec{u}_1 + (z_1\vec{u}_2 + ... + C_n\vec{u}_n)\}$$
  
 $C_1,..., C_n : any real #$ 

Fact

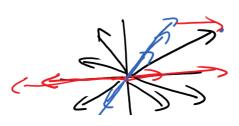
5 is in every span

Ex: Describe the span geometrically a) span  $\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ -3 \end{bmatrix}\right)$ 



Line through origin in R2
with d= [1]

b) Span  $\left( \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \end{bmatrix} \right)$ 



All of TR2 (whole xy-plane)

c) 
$$2bw \left( \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 8 \\ 0 \\ 8 \end{bmatrix} \right)$$

Line through origin in  $\mathbb{R}^3$  with  $d = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ 

d) span 
$$\left(\begin{bmatrix} 1\\2\\3 \end{bmatrix},\begin{bmatrix} -1\\0\\1 \end{bmatrix}\right)$$

Plane in IR3 through origin with direction vectors  $\vec{d}_1 = \begin{bmatrix} \frac{1}{3} \end{bmatrix}$  and  $\vec{d}_2 = \begin{bmatrix} -\frac{1}{3} \end{bmatrix}$ 

e) span 
$$\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}\right) = \mathbb{R}^3$$