

4.3 Finding Eigenvalues Cont'd

Ex: A is 5x5

$$|A - \lambda I| = (7-\lambda)^3 (9-\lambda)^2$$

Basis for $E_7 = \{ \begin{bmatrix}] \end{bmatrix} \}$

Basis for $E_9 = \{ \begin{bmatrix}] \end{bmatrix}, \begin{bmatrix}] \end{bmatrix} \}$

Eigenvalue

Algebraic Multiplicity

Geometric Mult.

$$\lambda = 7$$

$$3$$

$$1$$

$$\lambda = 9$$

$$2$$

$$2$$

FACT

For any eigenvalue,
geometric multiplicity \leq algebraic multiplicity

When geo. mult. = alg. mult. for all eigenvalues,
matrix A has a useful property (Section 4.4)

5 Facts about Eigenvalues

① A is invertible if and only if 0 is not an eigenvalue of A

A is invertible

$$\Leftrightarrow \det A \neq 0$$

$$\Leftrightarrow \det(A - 0I) \neq 0$$

$\Leftrightarrow 0$ is not an eigenvalue of A

② If A is invertible and $A\vec{x} = \lambda\vec{x}$
then \vec{x} is an eigenvector for A^{-1} with eigenvalue $\frac{1}{\lambda}$

$$A\vec{x} = \lambda\vec{x}$$

Mult by A^{-1} :

$$\underbrace{A^{-1}A\vec{x}}_{\vec{x}} = A^{-1}\lambda\vec{x}$$
$$\vec{x} = A^{-1}\lambda\vec{x}$$

$$\vec{x} = \lambda A^{-1}\vec{x} \quad (\lambda \text{ is a constant})$$

$$A^{-1}\vec{x} = \frac{1}{\lambda}\vec{x}$$

\nearrow eigenvector \nwarrow eigenvalue

③ If $A\vec{x} = \lambda\vec{x}$ then $A^n\vec{x} = \lambda^n\vec{x}$
for $n = 2, 3, 4, \dots$

$$A\vec{x} = \lambda\vec{x}$$

Mult. by A :

$$A^2\vec{x} = A\lambda\vec{x} = \lambda\underbrace{A\vec{x}}_{\lambda\vec{x}} = \lambda\lambda\vec{x} = \lambda^2\vec{x}$$

Quick Ex: A is invertible and has $\lambda = -1, 3$

Eigenvalues of A^{-1} : $-1, \frac{1}{3}$

Eigenvalues of A^n : $(-1)^n, 3^n$

From \dots \rightarrow \dots \rightarrow \dots \rightarrow \dots \rightarrow \dots \rightarrow \dots \rightarrow \dots

④ If $A\vec{x} = \lambda\vec{x}$ then \vec{x} is an eigenvector of $A+kI$ with eigenvalue $\lambda+k$

$$\begin{aligned}(A+kI)\vec{x} &= A\vec{x} + kI\vec{x} \\ &= \lambda\vec{x} + k\vec{x} \\ &= (\lambda+k)\vec{x}\end{aligned}$$

⑤ Suppose A has eigenvectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$ corresponding to $\lambda_1, \lambda_2, \dots, \lambda_m$.

$$A^k(c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_m\vec{v}_m) = c_1\lambda_1^k\vec{v}_1 + c_2\lambda_2^k\vec{v}_2 + \dots + c_m\lambda_m^k\vec{v}_m$$

- Generalization of Fact 3
- Coefficients are preserved

Ex: A is a 2×2 matrix with eigenvector $\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ corresponding to $\lambda_1 = -2$
 $\qquad\qquad\qquad \vec{v}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \qquad\qquad\qquad \lambda_2 = 3$

Find $A^3 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$