

4.1 Eigenvalues and Eigenvectors

Def

Let A be an $n \times n$ matrix.

If $A\vec{x} = \lambda\vec{x}$ for $\vec{x} \neq \vec{0}$ and some number λ , then λ is an eigenvalue of A and \vec{x} is an eigenvector of A .

Ex: Show that $\vec{x} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is an eigenvector of $A = \begin{bmatrix} 1 & -3 \\ 1 & 5 \end{bmatrix}$

$$A\vec{x} = \begin{bmatrix} 1 & -3 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ -4 \end{bmatrix}$$

$$= 4 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$= 4\vec{x}$$

($\lambda = 4$ is the eigenvalue)

Terminology: $\vec{x} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is an eigenvector of A corresponding to $\lambda = 4$

Note: $A\vec{0} = \lambda\vec{0}$ is always true
 $\vec{0}$ is not considered an eigenvector

Ex: Find all eigenvectors of $A = \begin{bmatrix} 3 & -2 \\ -3 & 4 \end{bmatrix}$ corresponding to $\lambda = 6$.

$$A\vec{x} = 6\vec{x}$$

$$A\vec{x} = 6I\vec{x}$$

$$A\vec{x} - 6I\vec{x} = \vec{0}$$

$$(A - 6I)\vec{x} = \vec{0}$$

Solve $[A - 6I \mid \vec{0}]$

$$A - 6I = \begin{bmatrix} 3 & -2 \\ -3 & 4 \end{bmatrix} - 6 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -3 & -2 \\ -3 & -2 \end{bmatrix}$$

Solve $\left[\begin{array}{cc|c} -3 & -2 & 0 \\ -3 & -2 & 0 \end{array} \right]$

$$\begin{array}{l} R_1 \\ -3 \end{array} \left[\begin{array}{cc|c} 1 & \frac{2}{3} & 0 \\ -3 & -2 & 0 \end{array} \right]$$

$$R_2 + 3R_1 \left[\begin{array}{cc|c} \textcircled{1} & \frac{2}{3} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

\uparrow
 $x_2 = t$

$$x_1 + \frac{2}{3}x_2 = 0$$

$$x_1 = -\frac{2}{3}t$$

eigenvectors $\vec{x} = \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} t \quad (t \neq 0)$

$$\text{or } \vec{x} = \begin{bmatrix} -2 \\ 3 \end{bmatrix} t \quad (t \neq 0)$$

Check :

$$\begin{aligned} A\vec{x} &= \begin{bmatrix} 3 & -2 \\ -3 & 4 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \end{bmatrix} \\ &= \begin{bmatrix} -12 \\ 18 \end{bmatrix} \\ &= 6 \begin{bmatrix} -2 \\ 3 \end{bmatrix} \quad \checkmark \end{aligned}$$

Fact

To find eigenvectors corresponding to eigenvalue λ : solve $[A - \lambda I \mid \vec{0}]$

Def

The eigenspace E_λ is the set of all eigenvectors of A corresponding to λ , plus the zero vector.
It's a subspace of \mathbb{R}^n .

E_λ :



Ex: Find a basis for the eigenspace E_3
for $A = \begin{bmatrix} 4 & 1 & -2 \\ -3 & 0 & 6 \\ 2 & 2 & -1 \end{bmatrix}$

Find eigenvectors : Solve $[A-3I | \vec{0}]$

$$\begin{bmatrix} 1 & 1 & -2 & | & 0 \\ -3 & -3 & 6 & | & 0 \\ 2 & 2 & -4 & | & 0 \end{bmatrix}$$

$x_1 \quad x_2 \quad x_3$

$$\begin{bmatrix} 1 & 1 & -2 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \text{ RREF}$$

$R_2 + 3R_1$
 $R_3 - 2R_1$

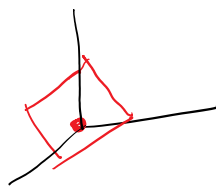
$x_2 = s$ $x_3 = t$

$$x_1 + x_2 - 2x_3 = 0 \quad \rightarrow \rightarrow \quad \boxed{x_1 = -s + 2t}$$

eigenvectors $\vec{x} = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} s + \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} t \quad (\vec{x} \neq \vec{0})$

basis for $E_3 = \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \right\}$

eigenspace E_3



Applications

① Vibrations

natural frequencies = eigenvalues

shapes/directions of vibrations = eigenvectors

② Facial Recognition

$$[\text{Image}] \rightarrow \begin{bmatrix} 0 & 18 & 253 \\ & & \dots \end{bmatrix}$$

eigenvectors = set of "basic" faces

Goal: Express any face as a linear combination of basic faces