

3.5 Subspaces and Dimension Gnt'd

Ch 7: Best-fit curve through a set of points
 Need column space and nullspace

Ex: $A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 0 & 0 \end{bmatrix}$ $A^T = \begin{bmatrix} 1 & 2 & 1 \\ 1 & 2 & 0 \\ 1 & 2 & 0 \end{bmatrix}$

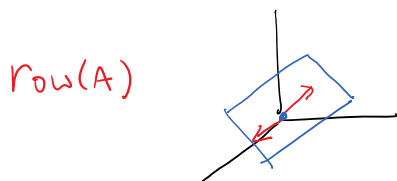
RREF of $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ RREF of $A^T = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

Find a basis for:

a) $\text{row}(A)$

Use nonzero rows of RREF/RREF

$\{ [1 \ 0 \ 0], [0 \ 1 \ 1] \}$



Basis for $\text{row}(A) = \{ [1 \ 0 \ 0], [0 \ 1 \ 1] \}$

b) $\text{col}(A)$

Use the leading entries of RREF as a guide

$\begin{bmatrix} \textcircled{1} & & \\ & \textcircled{1} & \\ & & \end{bmatrix}$

Use Columns 1 and 2 of A

basis for $\text{col}(A) = \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \right\}$

- Row ops change the column space (can't use RREF)
- Columns don't move around during row ops

c) $\text{row}(A)$, consisting of rows of A

$\text{row}(A) = \text{col}(A^T)$

Find a basis for $\text{col}(A^T)$

$$\text{RREF of } A^T = \begin{bmatrix} \textcircled{1} & & \\ & & \textcircled{1} \end{bmatrix}$$

Use Columns 1 and 3 of A^T

$$\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

$$\text{or } \{ [1 \ 1 \ 1], [1 \ 0 \ 0] \}$$

Ex: $A = \begin{bmatrix} 1 & 4 & 6 \\ 2 & 8 & 12 \end{bmatrix}$

Find a basis for $\text{null}(A)$

$$\text{null}(A) = \{ \vec{x} \text{ such that } A\vec{x} = \vec{0} \}$$

$$\text{Solve } A\vec{x} = \vec{0}$$

Each parameter gives a basis vector

$$\begin{array}{c} \begin{bmatrix} 1 & 4 & 6 & | & 0 \\ 2 & 8 & 12 & | & 0 \end{bmatrix} \\ \rightsquigarrow \begin{array}{ccc} x_1 & x_2 & x_3 \\ \begin{bmatrix} \textcircled{1} & 4 & 6 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \text{ RREF} \\ \begin{array}{cc} \uparrow & \uparrow \\ \boxed{x_2 = s} & \boxed{x_3 = t} \end{array} \end{array} \end{array}$$

$$x_1 + 4x_2 + 6x_3 = 0 \rightarrow \boxed{x_1 = -4s - 6t}$$

$$\vec{x} = \begin{bmatrix} -4 \\ 1 \\ 0 \end{bmatrix} s + \begin{bmatrix} -6 \\ 0 \\ 1 \end{bmatrix} t$$

$$\text{Basis for } \text{null}(A) = \left\{ \begin{bmatrix} -4 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -6 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Ex: Find a basis for $\text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ 24 \end{bmatrix} \right)$

Method I $A = \begin{bmatrix} \textcircled{1} \\ \textcircled{1} \\ \textcircled{1} \end{bmatrix}$

Find a basis for $\text{row}(A)$

Method II $A = [0 \ 0 \ 0]$

Method II

$$A = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$

Find a basis for $\text{col}(A)$

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 6 \\ 1 & 5 & 24 \end{bmatrix}$$

Find a basis for $\text{row}(A)$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & -6 \\ 0 & 1 & 6 \\ 0 & 0 & 0 \end{bmatrix} \text{ RREF}$$

$$\text{Basis} = \left\{ \begin{bmatrix} 1 & 0 & -6 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 6 \end{bmatrix} \right\}$$

Def

Given a basis $\mathcal{B} = \{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \}$ of \mathbb{R}^n ,
the Coordinate Vector of \vec{v} is

$$[\vec{v}]_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \text{ such that } \vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

Ex: Find $[\vec{v}]_{\mathcal{B}}$ for $\vec{v} = \begin{bmatrix} 5 \\ 15 \\ 28 \end{bmatrix}$

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 4 \end{bmatrix} \right\}$$

$$\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3$$

$$\begin{array}{ccc} c_1 & c_2 & c_3 \\ \left[\begin{array}{ccc|c} 1 & 1 & 1 & 5 \\ 2 & 5 & 1 & 15 \\ 3 & 6 & 4 & 28 \end{array} \right] \end{array}$$

$$\rightsquigarrow \begin{array}{ccc} c_1 & c_2 & c_3 \\ \left[\begin{array}{ccc|c} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 4 \end{array} \right] \text{ RREF} \end{array}$$

$$\begin{array}{l} c_1 = -2 \\ c_2 = 3 \\ c_3 = 4 \end{array}$$

$$\text{Therefore } [\vec{v}]_{\mathcal{B}} = \begin{bmatrix} -2 \\ 3 \\ 4 \end{bmatrix}$$