

① Show that  $A\vec{v} = \lambda\vec{v}$

$$\begin{aligned} A\vec{v} &= \begin{bmatrix} 0 & 3 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 3 \\ 3 \end{bmatrix} \\ &= 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

The eigenvalue is  $\lambda = 3$ .

③ Show that  $A\vec{v} = \lambda\vec{v}$

$$\begin{aligned} A\vec{v} &= \begin{bmatrix} -1 & 1 \\ 6 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \end{bmatrix} \\ &= \begin{bmatrix} -3 \\ 6 \end{bmatrix} \\ &= -3 \begin{bmatrix} 1 \\ -2 \end{bmatrix} \\ &= -3\vec{v} \end{aligned}$$

The eigenvalue is  $\lambda = -3$ .

(5) Show that  $A\bar{v} = \lambda\bar{v}$

$$\begin{aligned} A\bar{v} &= \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & -2 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 6 \\ -3 \\ 3 \end{bmatrix} \\ &= 3 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \\ &= 3\bar{v} \end{aligned}$$

The eigenvalue is  $\lambda = 3$ .

(7) To find eigenvectors, solve  $[A - \lambda I | \vec{0}]$

$$\begin{aligned} & [A - 3I | \vec{0}] \\ & \begin{bmatrix} -1 & 2 & | & 0 \\ 2 & -4 & | & 0 \end{bmatrix} \\ \frac{R_1}{-1} & \begin{bmatrix} 1 & -2 & | & 0 \\ 2 & -4 & | & 0 \end{bmatrix} \\ R_2 - 2R_1 & \begin{bmatrix} 1 & -2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \\ & \quad \uparrow \\ & \quad x_2 = t \end{aligned}$$

$$x_1 - 2x_2 = 0 \Rightarrow x_1 = 2t$$

$$\bar{x} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} t$$

One eigenvector is  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

$$A \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ -3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} \checkmark$$

(11) To find eigenvectors, solve  $[A - \lambda I | \vec{0}]$

$$[A + I | \vec{0}]$$

$$\left[ \begin{array}{ccc|c} 2 & 0 & 2 & 0 \\ -1 & 2 & 1 & 0 \\ 2 & 0 & 2 & 0 \end{array} \right]$$

$$\frac{R_1}{2} \left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ -1 & 2 & 1 & 0 \\ 2 & 0 & 2 & 0 \end{array} \right]$$

$$\begin{array}{l} R_2 + R_1 \\ R_3 - 2R_1 \end{array} \left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 2 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\frac{R_2}{2} \left[ \begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

↑

$$x_3 = t$$

$$x_1 + x_3 = 0 \Rightarrow x_1 = -t$$

$$x_2 + x_3 = 0 \Rightarrow x_2 = -t$$

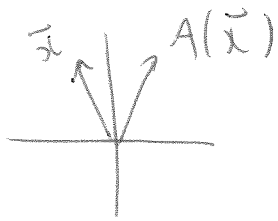
$$\vec{x} = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} t$$

One eigenvector is  $\begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$ .

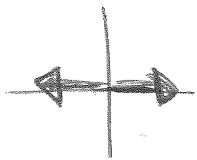
Another one is  $\begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix}$ .

$$A \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 \\ -1 & 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \quad \checkmark$$

(13) Reflection in the y-axis



For which  $\vec{x}$  are  $\vec{x}$  and  $A\vec{x}$  multiples of one another?



If  $\vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  then  $A\vec{x} = -1\vec{x}$

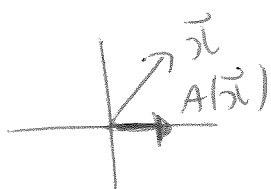


If  $\vec{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  then  $A\vec{x} = 1\vec{x}$

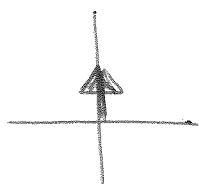
$$\lambda = 1 \quad E_1 = \text{span} \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

$$\lambda = -1 \quad E_{-1} = \text{span} \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$$

(15) Projection onto the  $x$ -axis



For which  $\vec{x}$  are  $\vec{x}$  and  $A\vec{x}$  multiples of one another?



If  $\vec{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  then  $A\vec{x} = 0 \vec{x}$

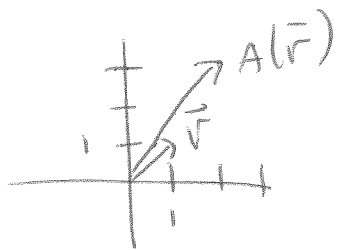


If  $\vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  then  $A\vec{x} = 1\vec{x}$

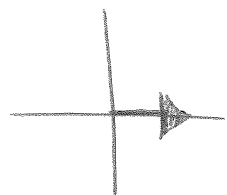
$$\lambda = 1 \quad E_1 = \text{span} \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$$

$$\lambda = 0 \quad E_0 = \text{span} \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

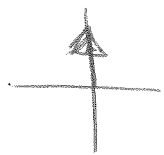
(17) Stretch by a factor of 2 horizontally  
and a factor of 3 vertically.



For which  $\vec{x}$  are  $\vec{x}$  and  $A\vec{x}$   
multiples of one another?



$$\text{If } \vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ then } A\vec{x} = 2\vec{x}$$



$$\text{If } \vec{x} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ then } A\vec{x} = 3\vec{x}$$

$$\lambda = 2 \quad E_2 = \text{span} \left( \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$$

$$\lambda = 3 \quad E_3 = \text{span} \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

(23) To find the eigenvalues solve

$$\det(A - \lambda I) = 0$$

$$\begin{vmatrix} 4-\lambda & -1 \\ 2 & 1-\lambda \end{vmatrix} = 0$$

$$(4-\lambda)(1-\lambda) + 2 = 0$$

$$\lambda^2 - 5\lambda + 4 + 2 = 0$$

$$\lambda^2 - 5\lambda + 6 = 0$$

$$(\lambda - 2)(\lambda - 3) = 0$$

$$\lambda = 2, 3$$

$E_2$ : Solve  $[A - 2I \mid \vec{0}]$

$$\left[ \begin{array}{cc|c} 2 & -1 & 0 \\ 2 & -1 & 0 \end{array} \right]$$

$$\frac{R_1}{2} \left[ \begin{array}{cc|c} 1 & -\frac{1}{2} & 0 \\ 2 & -1 & 0 \end{array} \right]$$

$$R_2 - 2R_1 \left[ \begin{array}{cc|c} 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\uparrow \\ x_2 = t$$

$$x_1 - \frac{1}{2}x_2 = 0 \Rightarrow x_1 = \frac{1}{2}t$$

$$\vec{x} = \begin{bmatrix} \frac{1}{2} \\ 1 \\ 0 \end{bmatrix} t \text{ or } \vec{x} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} t$$

$$\text{Basis for } E_2 = \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \right\}$$

→

(23) Cont'd

$E_3$ : Solve  $[A - 3I | \vec{0}]$

$$\left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 2 & -2 & 0 \end{array} \right]$$

$$R_2 - 2R_1 \left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\uparrow \\ x_2 = t$$

$$x_1 - x_2 = 0 \Rightarrow x_1 = t$$

$$\vec{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} t$$

Basis for  $E_3 = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

Illustration of  $A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

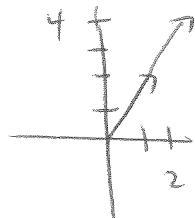
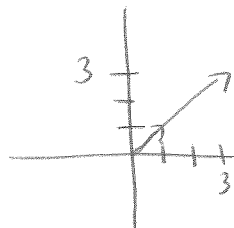


Illustration of  $A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$





(25) To find the eigenvalues solve

$$\det(A - \lambda I) = 0$$

$$\begin{vmatrix} 2-\lambda & 5 \\ 0 & 2-\lambda \end{vmatrix} = 0$$

$$(2-\lambda)^2 = 0$$

$$\lambda = 2, 2$$

$E_2$  = Solve  $[A - 2I | \vec{0}]$

$$\left[ \begin{array}{cc|c} 0 & 5 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\frac{R_1}{5} \left[ \begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

↑

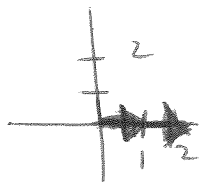
$$x_1 = t$$

$$x_2 = 0$$

$$\vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} t$$

Basis for  $E_2 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$

Illustration of  $A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$



(37) To find the eigenvalues solve

$$\det(A - \lambda I) = 0$$

$$\begin{vmatrix} a-\lambda & b \\ 0 & d-\lambda \end{vmatrix} = 0$$

$$(a-\lambda)(d-\lambda) = 0$$

$$\lambda = a, d$$

We assume  $a \neq d$ .

$E_a$ : Solve  $[A - aI | \vec{0}]$

$$\begin{bmatrix} 0 & b & | & 0 \\ 0 & d-a & | & 0 \end{bmatrix}$$

$$\frac{R_1}{b} \begin{bmatrix} 0 & 1 & | & 0 \\ 0 & d-a & | & 0 \end{bmatrix}$$

$$R_2 - (d-a)R_1 \begin{bmatrix} 0 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

Note: If  $b$  happens to be 0 then do a row swap to get:

$$\begin{bmatrix} 0 & d-a & | & 0 \\ 0 & b & | & 0 \end{bmatrix}$$

The RREF is still  $\begin{bmatrix} 0 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$

$$\begin{matrix} \uparrow \\ x_1 = t \\ x_2 = 0 \end{matrix}$$

$$\vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} t$$

Basis for  $E_a = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$

$$\text{Check: } A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a & b \\ 0 & d \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ 0 \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \end{bmatrix} \checkmark$$



$f_2$  : Solve  $[A - dI \mid \vec{0}]$

$$\begin{bmatrix} a-d & b & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\frac{R_1}{a-d} \begin{bmatrix} 1 & \frac{b}{a-d} & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\uparrow \\ x_2 = t$$

$$x_1 + \frac{b}{a-d} x_2 = 0 \Rightarrow x_1 = \frac{-b}{a-d} t$$

$$\vec{x} = \begin{bmatrix} \frac{-b}{a-d} \\ 1 \end{bmatrix} t$$

$$\text{or } \vec{x} = \begin{bmatrix} -b \\ a-d \end{bmatrix} t$$

$$\text{or } \vec{x} = \begin{bmatrix} b \\ d-a \end{bmatrix} t$$

Basis for  $\epsilon_d = \left\{ \begin{bmatrix} b \\ d-a \end{bmatrix} \right\}$

$$\text{Check: } A \begin{bmatrix} b \\ d-a \end{bmatrix} = \begin{bmatrix} a & b \\ 0 & d \end{bmatrix} \begin{bmatrix} b \\ d-a \end{bmatrix} = \begin{bmatrix} ab + bd - ab \\ d(d-a) \end{bmatrix} = d \begin{bmatrix} b \\ d-a \end{bmatrix} \checkmark$$